



MATH 251

Matrix Algebra for Engineers

Instructor: Gilles Cazelais

Office: CBA 158 (phone number: 370-4495)

Office hours: <http://pacificcoast.net/~cazelais/schedule.html>

Email address: cazelais@camosun.bc.ca

Course web page: <http://pacificcoast.net/~cazelais/251.html>

Textbook

Linear Algebra, A Modern Introduction (3rd Edition) by David Poole.

Calculator Policy

Only scientific calculators are allowed for the tests and final exam. Programmable or graphing calculators are not allowed.

Evaluation

- Three term tests: 50%
- Comprehensive final exam: 50%

To pass the course, a student must get at least 50% on the final exam.

If your term work is at least 50% and you get 60% or higher in the final exam, then you will receive a C in the course even if your overall average is under 60%.

Otherwise, the following percentage conversion to letter grade will be used:

| | | | | | | | | | | |
|---------------|------|-------|-------|-------|-------|-------|-------|-------|-------|--------|
| Percentage: | 0-49 | 50-59 | 60-64 | 65-69 | 70-72 | 73-76 | 77-79 | 80-84 | 85-89 | 90-100 |
| Letter grade: | F | D | C | C+ | B- | B | B+ | A- | A | A+ |

Tentative Schedule

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|---------------|------------|---------------|------------|---------------|-------------|
| Test 1 | October 18 | Test 2 | November 8 | Test 3 | November 29 |
|---------------|------------|---------------|------------|---------------|-------------|

Final exams are held from December 12 - 20. You must be available at the scheduled time.

Course Outline

1. VECTORS
 - The Geometry and Algebra of Vectors (1.1)
 - Length and Angle: The Dot Product (1.2)
 - Lines and Planes (1.3)
 - Exploration: The Cross Product
2. SYSTEMS OF LINEAR EQUATIONS
 - Introduction to Systems of Linear Equations (2.1)
 - Direct Methods for Solving Linear Systems (2.2)
 - Spanning Sets and Linear Independence (2.3)
 - Applications (2.4)

3. MATRICES
 - Matrix Operations (3.1)
 - Matrix Algebra (3.2)
 - The Inverse of a Matrix (3.3)
 - The LU Factorization (3.4)
 - Subspaces, Basis, Dimensions, and Rank (3.5)
 - Introductions to Linear Transformations (3.6)
4. Complex Numbers (Appendix C)
5. EIGENVALUES AND EIGENVECTORS
 - Introduction to Eigenvalues and Eigenvectors (4.1)
 - Determinants (4.2)
 - Exploration: Geometric Applications of Determinants
 - Eigenvalues and Eigenvectors of $n \times n$ matrices (4.3)
 - Similarity and Diagonalization (4.4)
 - Applications (4.6)
6. ORTHOGONALITY
 - Orthogonality in \mathbb{R}^n (5.1)
 - Orthogonal Complements and Orthogonal Projections (5.2)
 - The Gram-Schmidt Process and the QR Factorization (5.3)
 - Orthogonal Diagonalization of Symmetric Matrices (5.4)
7. DISTANCE AND APPROXIMATION
 - Least Squares Approximation (7.3)

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